

# Mobility Data Management & Exploration

Ch. 01. Introduction

#### Nikos Pelekis & Yannis Theodoridis

InfoLab | University of Piraeus | Greece infolab.cs.unipi.gr

v.2014.05



#### "Τά πάντα ρεί, μηδέποτε κατά τ' αυτό μένειν – Everything changes, nothing remains still." Heraclitus

# Chapter outline



- 1.1. About Mobility Data
- 1.2. What Can We Learn from Mobility Data
- 1.3. Location- and Mobility-Aware Applications
- 1.4. Adding Mobility in Spatial Database Systems
- 1.5. Summary



1.1. About Mobility Data

#### Mobile devices and services



■ Large diffusion of mobile devices, mobile services and location-based services → location- and mobility-aware data



### Which data?

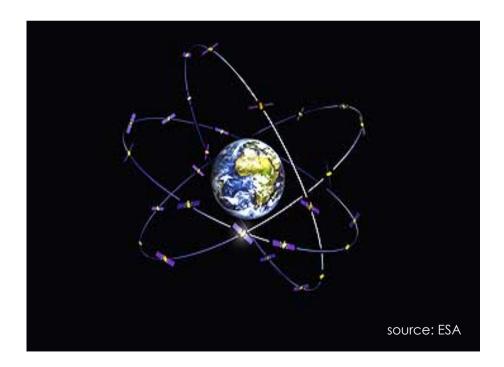


- Location data from mobile phones
  - i.e., cell positions in the GSM/UMTS network
- Location (and trajectory) data from GPS devices
  - Humans (pedestrians, drivers) carrying GPS-equipped smartphones
  - Vessels equipped with AIS transmitters (due to maritime regulations)
- Location data from indoor posistioning systems
  - RFIDs (radio-frequency ids)
  - Wi-Fi access points
     Bluetooth sensors
     Taj Mahal Category: Monuments Distance: 236 m Agra, India

# Geo-positioning



- Positioning technologies using information from satellites
  - Global Positioning System (GPS) and its variations ...
  - Assisted GPS (A-GPS); Differential GPS (D-GPS)

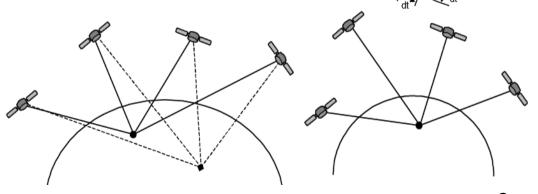


# Geo-positioning (cont.)



#### GPS (Global Positioning System)

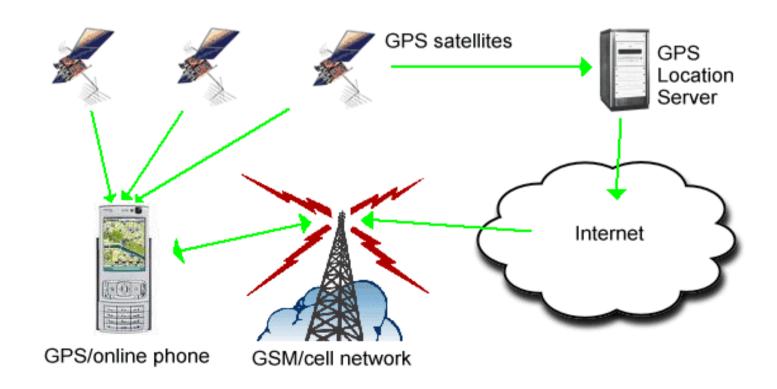
- 24-satellite constellation
  - monitored by 5 monitoring stations and 4 ground antennas;
     handled with (extremely precise) atomic clocks
  - At least 5 satellites are in view from every point on the globe
- GPS receiver gathers information from 4 (or 3, the minimum) satellites and
  - triangulates to position itself;
  - fixes its (non-atomic) clock
- Position accuracy: ~20m



# Geo-positioning (cont.)



- GPS accuracy improvements
  - Assisted GPS (A-GPS): provides pre-calculated satellite orbits to the receiver; accuracy ~10m
  - Differential GPS (D-GPS): combines with land (antennas) information; accuracy down to 1m



# Geo-positioning (cont.)



- GPS competitors
  - Glonass (Russia) currently, semi-operational
    - 24-satellite constellation; 1-10m accuracy
  - Galileo (EU) to be fully operational by 2019
    - 30-satellite constellation; 1m accuracy
  - **Beidou** (China) to be fully operational by 2020
    - 35-satellite constellation; 10m accuracy







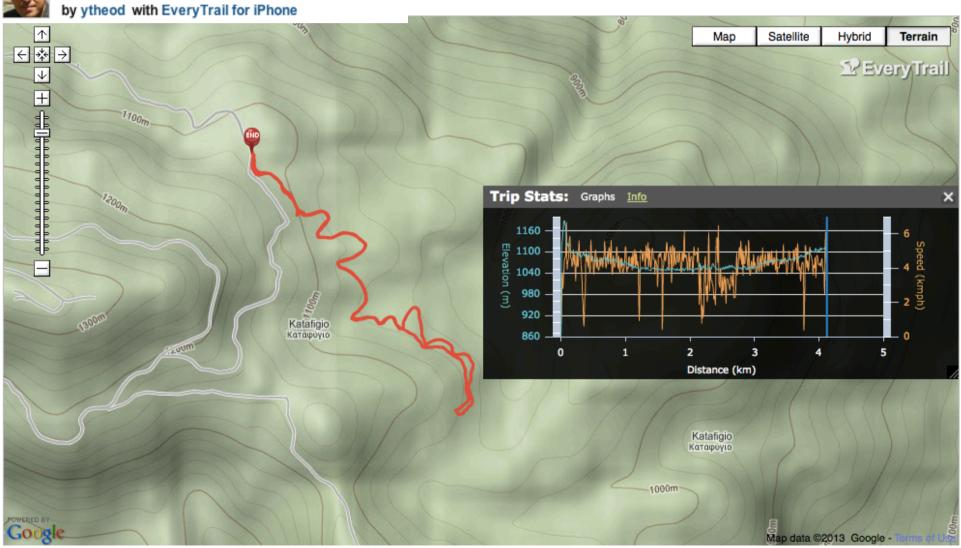


# GPS data – an example





Parnitha, Jan. 2013 - Attica, Greece



#### GPS data – format



Raw data: GPS recordings (.gpx format)

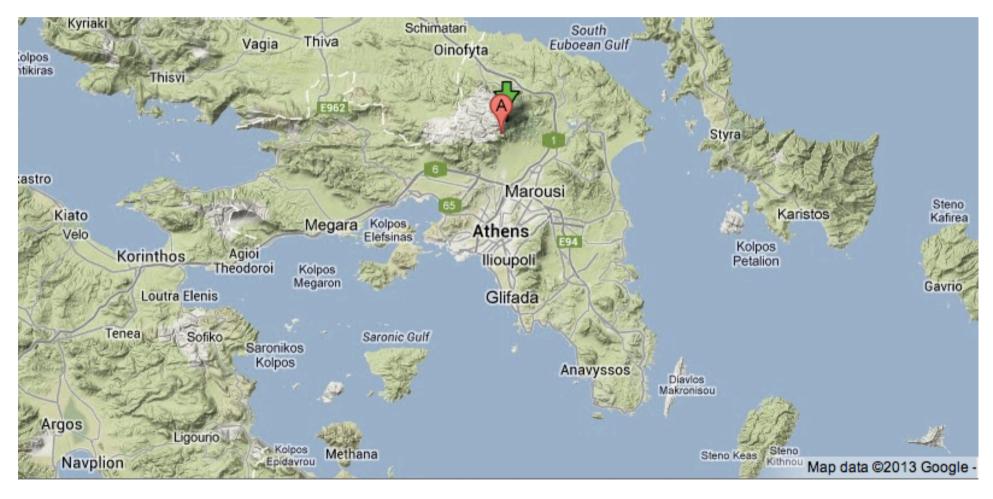
```
<trk>
<trkpt lat="38.17733919" lon="23.74038222"> <ele>862.62</ele>
         <time>2013-01-19T08:54:57.608Z</time> </trkpt>
<trkpt lat="38.17725880" lon="23.74043843"> <ele>1117.98</ele>
         <time>2013-01-19T08:55:21.609Z</time> </trkpt>
<trkpt lat="38.17717291" lon="23.74039676"> <ele>1129.98</ele>
         <time>2013-01-19T08:55:31.608Z</time> </trkpt>
<trkpt lat="38.17707471" lon="23.74038878"> <ele>1155.93</ele>
         <time>2013-01-19T08:55:45.584Z</time> </trkpt>
</trk>
```

## GPS data – format (cont.)



■ Where and when?

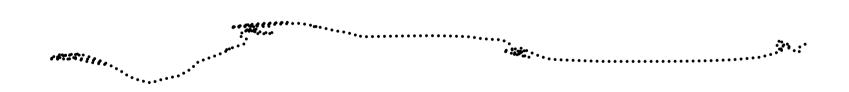
<trkpt lat="38.17733919" lon="23.74038222"> <time>2013-01-19T08:54:57.608Z</time>



#### From GPS data to trajectories



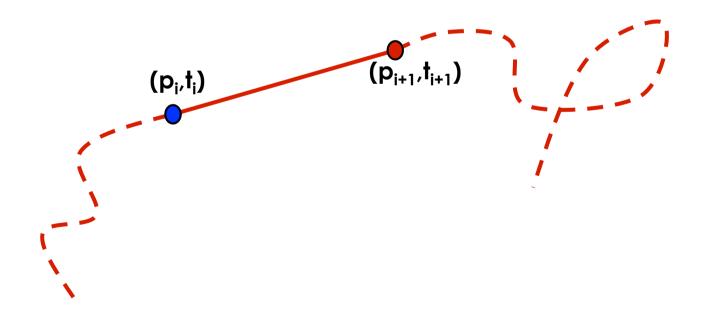
- A trajectory is a model for a motion path of a moving object (human, animal, robot, ...)
  - (due to discretization) a sequence of sampled time-stamped locations (p<sub>i</sub>, t<sub>i</sub>) where:
    - $\blacksquare$  p<sub>i</sub> is a 2D point  $(x_i, y_i)$  and
    - t<sub>i</sub> is the recording timestamp of p<sub>i</sub>



#### From GPS data to trajectories (cont.)



- A common representation of a trajectory is a 3D polyline whose vertices correspond to time-stamped locations (p<sub>i</sub>, t<sub>i</sub>)
  - Usually, **linear interpolation** is assumed between  $(p_i, t_i)$  and  $(p_{i+1}, t_{i+1})$



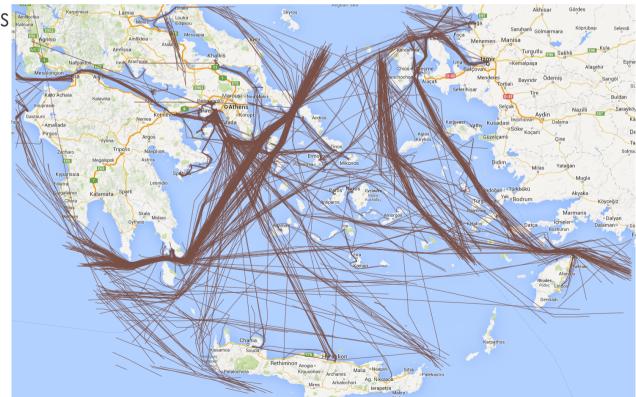
# Examples of trajectory datasets



#### Vessels sailing on the sea

- Example: "IMIS%" datasets, available at <u>ChoroChronos.org</u>
- IMIS-3-days statistics:
  - ~3 million GPS recordings from 933 vessels sailing in Aegean sea during a 3 days period

1500 trajectories

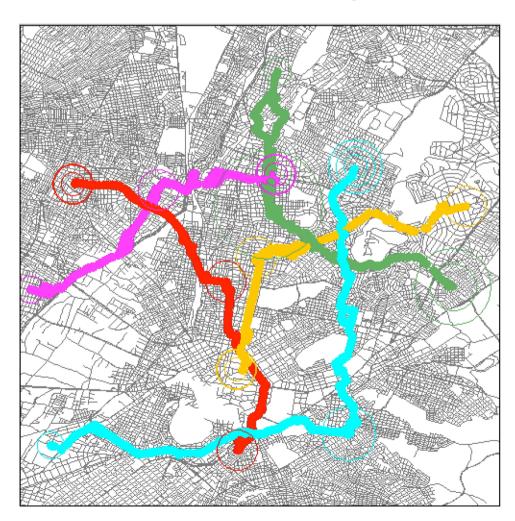


#### Examples of trajectory datasets



#### Vehicles moving on a road network

- Example: "Attiki" dataset, available at <a href="http://infolab.cs.unipi.gr/hermes/">http://infolab.cs.unipi.gr/hermes/</a>
- Produced by Hermoupolis data generator
- Statistics:
  - ~1.5 million GPS recordings of vehicles moving in Athens metropolitan area road network
  - ~4,500 trajectories



1.2.

What Can We Learn from Mobility Data

#### Learning from vessels datasets

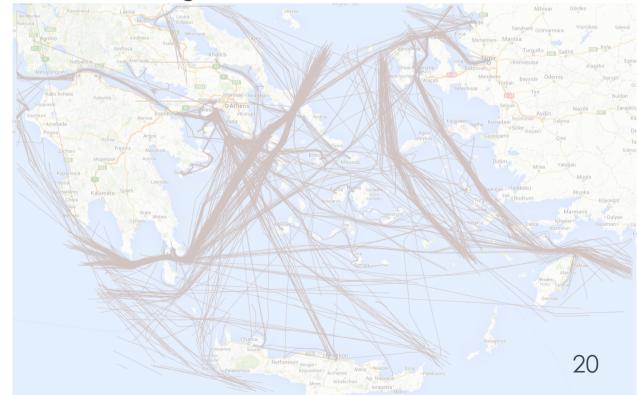


- Analysis at **individual level** (i.e. per vessel):
  - Draw a vessel track (detailed vs. <u>simplified</u>)
  - Calculate <u>similarity</u> between a vessel's actual and expected route
  - Calculate minimum <u>distance</u> between a vessel's track and the shore (where and when)
  - Calculate maximum number of vessels in a vessel's vicinity (e.g. 10 n.m. radius)
  - Find whether (and how many times) a vessel sailed through narrow passages or biodiversity boxes
  - Find whether (and how many times) a vessel has performed sharp changes in its direction
  - etc.

## Learning from vessels datasets (cont.)



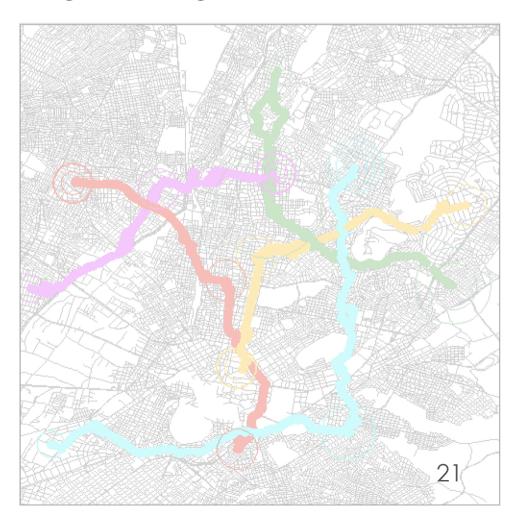
- Analysis at collective level (i.e. per population of vessels)
  - Find the <u>most popular</u> among vessels' routes as well as the <u>outliers</u>
  - Calculate the Origin-Destination (OD) matrix
  - Calculate the population's environmental fingerprint
  - Search for correlation between flags of convenience and outliers
  - etc.



#### Learning from vehicles datasets



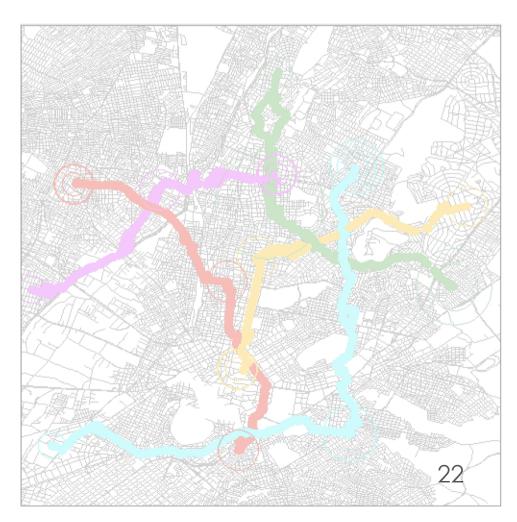
- (holistic) Traffic analysis
  - How many cars are <u>currently moving on</u> the ring of the town?
  - What is the queue per traffic light?
  - Does the "green wave" between traffic lights appear as it has been designed?
  - Which cars follow eco-driving recommendations?



## Learning from vehicles datasets (cont.)



- (personalized) Location-aware services
  - Where is my <u>nearest</u> restaurant?
  - Which gas stations are at a maximum of 3 km <u>deviation</u> from my planned trip?
  - Are there any Facebook friends <u>around</u>?

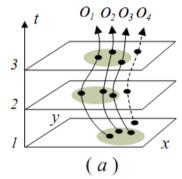


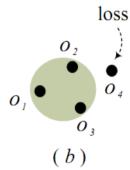
### Learning from mobility data

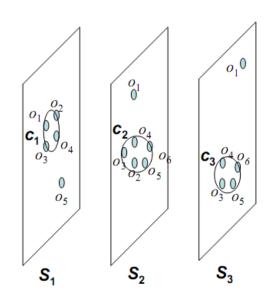


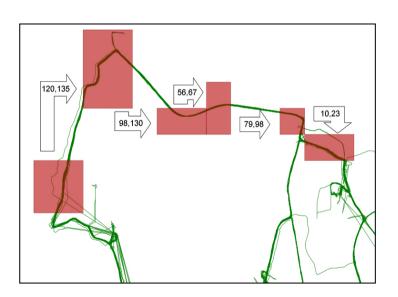
■ More ambitious patterns, extracted by KDD techniques. Examples:  $o_1 o_2 o_3 o_4$ 

- **Typical routes** (clusters vs. outliers): T-Patterns, hot motion paths, etc.
- Flows of movement: moving clusters, flocks, convoys, etc.









1.3.

Location- and Mobility-Aware Applications

## Location-based services (LBS)



- Navigation (vehicle or pedestrian) & Location-aware information
  - Routing, finding the nearest point-of-interest (POI)
  - Location-based yellow pages ("what-is-around", ...)

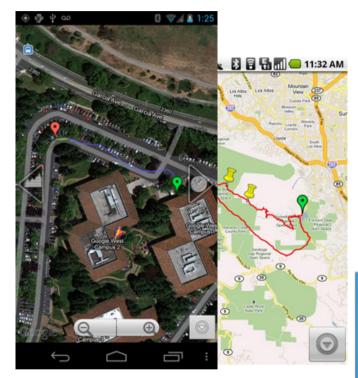
#### Resource management & Tracking

- (taxis, trucks, etc.) fleet management, administration of container goods, location-based charging
- Tracing of a stolen car, locating persons in an emergency situation, ...

#### Location-aware social networking

Google Latitude, Facebook places, Foursquare, etc.

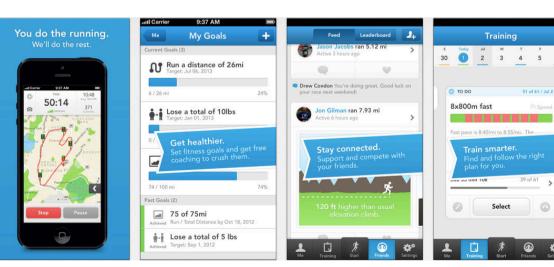
## Commercial examples



**Google My Tracks** 



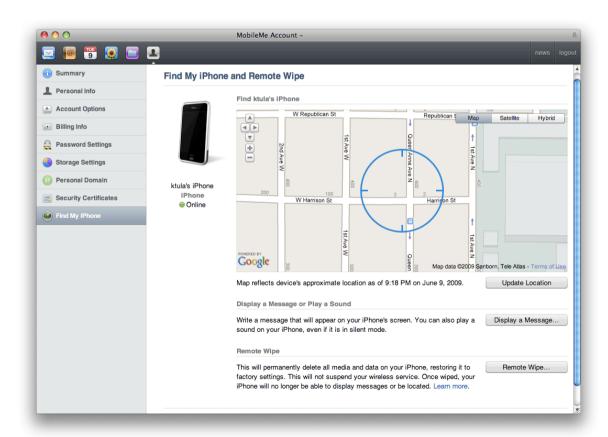
**EveryTrail** 



RunKeeper



- Tracing lost or stolen products
  - Lost smartphones: "Find my iPhone", "Where's my Droid" etc.
  - Stolen cars: "Volvo connectivity"



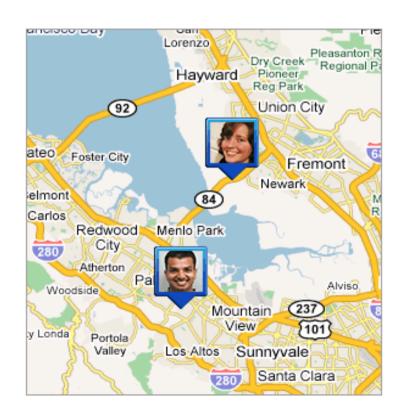








See in real time **where** your friends are! (launched Feb.09 by Google)







# Google places

- Google places: Rate and share places on Google
  - Google places for business:
    - (business perspective) Get your business found on Google
    - (end user's perspective) rate products, search for similar, compare prices, etc.











 Tag yourselves and find tagged friends



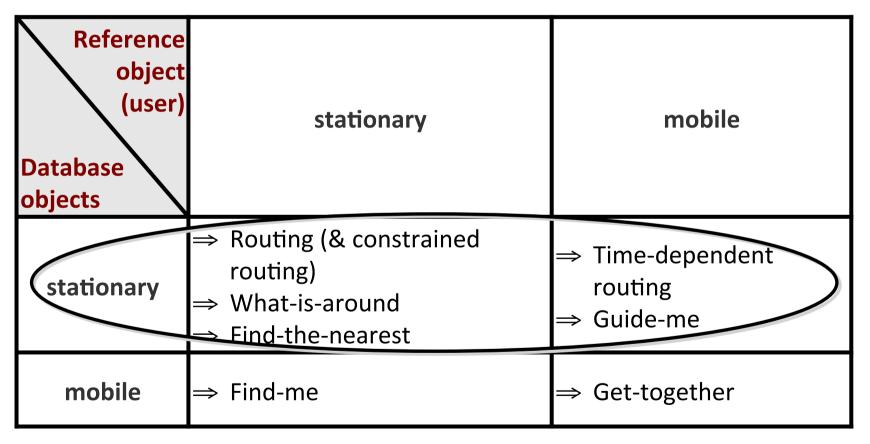


 Tell your friends where you are, suggest places, etc.

#### Taxonomy of location-aware apps



With respect to mobility of involved objects

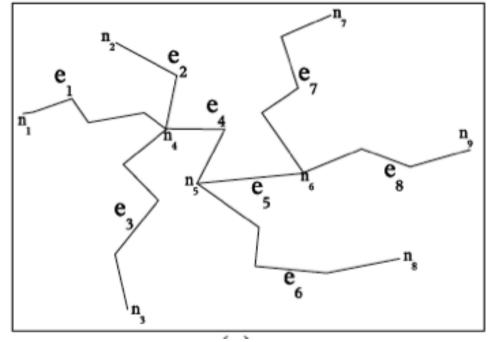


Interesting: the vast majority of current commercial apps are classified as stationary

## (underlying) Transportation network



- Transportation networks are usually modeled as directed graphs G(N, E)
  - N: set of nodes
  - E: set of edges between nodes
- Alternative models\*:
  - Edge-oriented model
    - edges  $<e_1>$ ,  $<e_2$ ,  $e_3>$ , etc.
  - Route-oriented model
    - Routes  $\langle e_2, e_3 \rangle$ , etc.

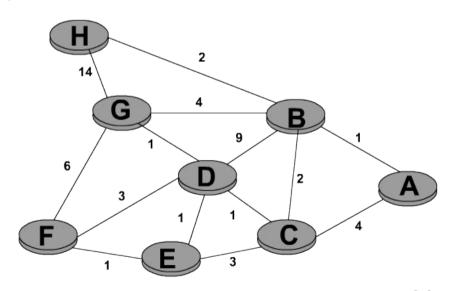


<sup>\*</sup> See more details in Chap. 3

# "Routing"



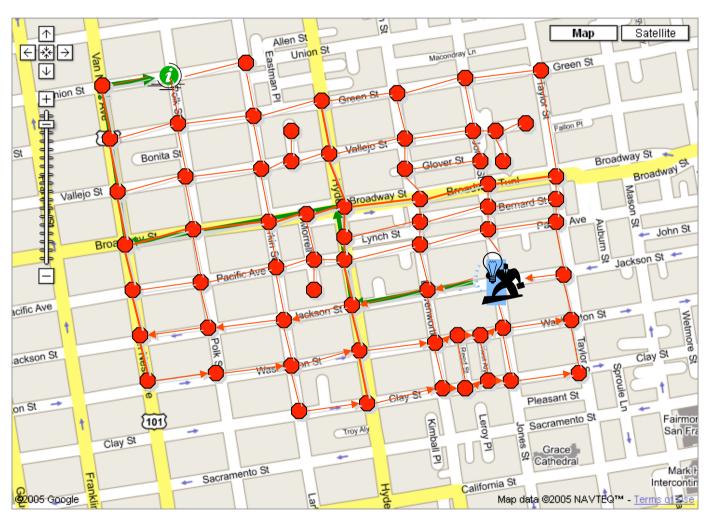
- (aka "Get Directions" in Google maps)
- Find the optimal route from a departure to a destination point
  - Goal to be optimized: the minimal network distance traveled; the minimal traveled time; etc.
- Relates to the well-known shortest path (SP) problem from graph theory and network analysis
  - Several off-the-shelf solutions, e.g. Dijkstra's single-start SP algorithm
  - Recall the SP problem: "find the SP from A to D"



# "Routing" (cont.)



■ Example:



# "Constrained routing"



(currently, not supported in Google maps!)

- Find the optimal route from a departure to a destination point ...
  - ... with the extra constraint to pass through one among a specified set of candidate points
  - Example: "Find the best route office-to-home constrained to pass from a bank ATM"
  - Issue: how to find (efficiently) the best deviation?
  - Technically, a variation of SP problem\*

Allen St.

Wallejo St.

Broadway St.

Broadw

<sup>\*</sup> See more details in Chap. 3

#### "What-is-around"



- (aka "Search nearby" in Google maps)
- Retrieve and display all points of interest (POI) located in the surrounding area
  - Usually rectangular or circular area
  - Example: "Find all gas-stations within a distance of 1km from my current location"
  - As simple as a typical range query\* in Spatial Databases

Allen St.

<sup>\*</sup> See more details in Chap. 2

### "Find-the-nearest"



(currently, not supported in Google maps!)

 Retrieve and display the nearest POI (restaurants, museums, etc.) with respect to a reference location

Example: "find the nearest bank ATM w.r.t. my current location"

Issue: distance is computed over the network rather than the

free (Euclidean) space

■ How to solve it efficiently?\*

Allen St.

Map Satellife

Green St.

Wallejo St.

Wallejo St.

Broadway St.

Broadway

<sup>\*</sup> See more details in Chap. 3

# "Find me" / "Get-together"



- Several moving objects try to reach a stationary / moving object
  - Could be an advanced "Google Latitude" or "Facebook Places" app
- How-to:
  - other objects are routed to a point where the target object is estimated to arrive after a time interval
  - the "meeting point" is periodically refreshed
  - Challenge: future location prediction\*



<sup>\*</sup> See more details in Chap. 7

1.4.

Adding Mobility in Spatial Database Systems

## From the DBMS perspective ...



- So far, we've outlined a variety of mobile-aware applications
  - from 'smart' (updated in real-time) routing ...
  - ... to mobile social networking (Google Latitude, Facebook Places, etc.)
- Internally (either at server or client side), what kinds of operations should be efficiently supported?
  - Spatial database and graph-based operations
  - Trajectory management operations

## Operations to be supported



- Spatial database and graph-based operations
  - Window search: select points within a (circular or rectangular) window
  - k-NN search: select the k- nearest points to an object (point or region)
  - Routing: find the optimal route between two points (taking into consideration a number of constraints)
- Trajectory management operations
  - **.**..

## Operations to be supported (cont.)

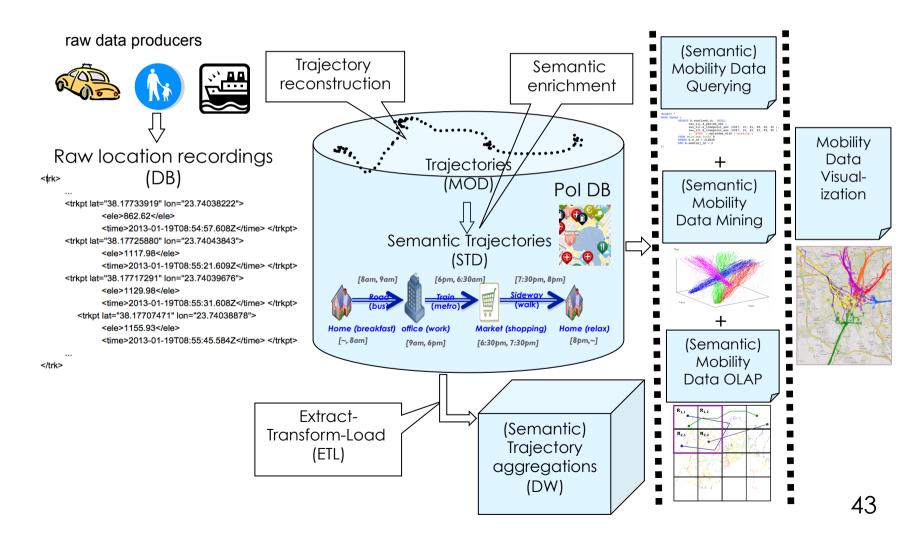


- Spatial database and graph-based operations
- Trajectory management operations
  - Trajectory update (& map-matching): add a new coming position to an existing trajectory (mapped to the underlying network)
  - Trajectory-based search: perform (spatial and/or temporal) range, NN, trajectory similarity, etc. search
  - Trajectory projection: estimate the anticipated position of an object at a future time (perhaps, taking its history into consideration)

## The big picture



■ raw GPS data → (raw & semantic) trajectories → mobility patterns



#### raw data producers







# Trajectory reconstruction

Semantic enrichment

# Raw location recordings < (DB)</p>

...

<trkpt lat="38.17733919" lon="23.74038222">

<ele>862.62</ele>

<time>2013-01-19T08:54:57.608Z</time> </trkpt>

<trkpt lat="38.17725880" lon="23.74043843">

<ele>1117.98</ele>

<time>2013-01-19T08:55:21.609Z</time> </trkpt>

<trkpt lat="38.17717291" lon="23.74039676">

<ele>1129.98</ele>

<time>2013-01-19T08:55:31.608Z</time> </trkpt>

<trkpt lat="38.17707471" lon="23.74038878">

<ele>1155.93</ele>

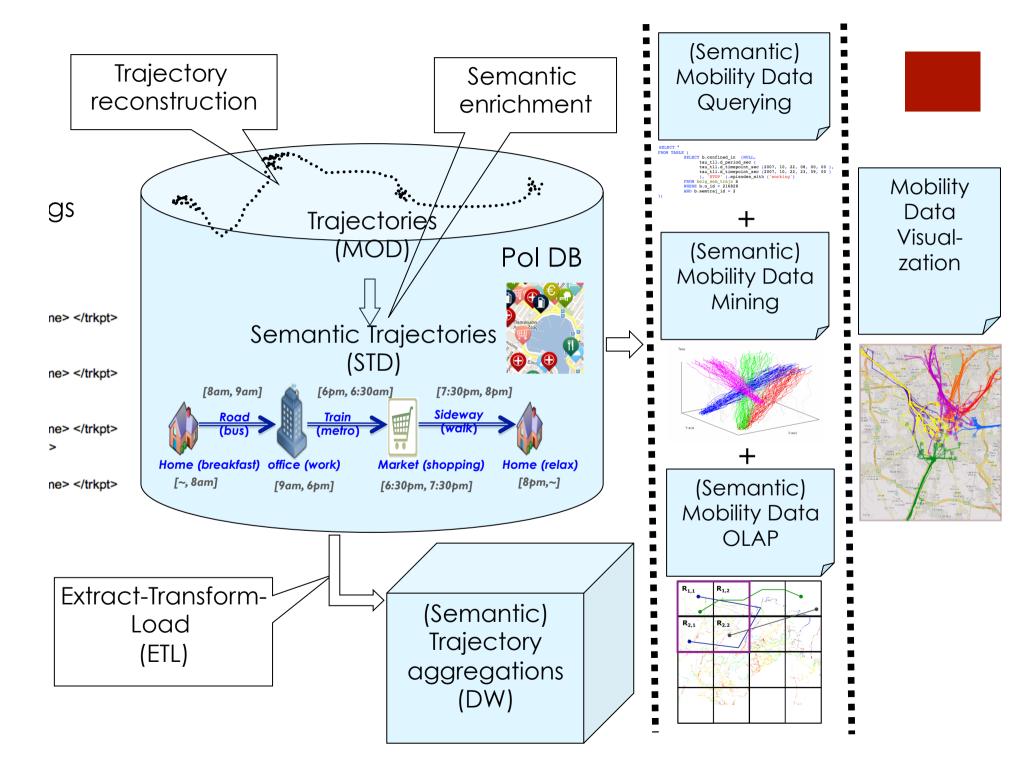
<time>2013-01-19T08:55:45.584Z</time> </trkpt>

Trajectories (MOD) Pol DB Semantic Trajectories (STD) [6pm, 6:30am] [8am, 9am] [7:30pm, 8pm] **Sideway** Home (breakfast) office (work) Market (shopping) Home (relax) [~, 8am] [8pm,~] [6:30pm, 7:30pm] [9am, 6pm]

</trk>

Extract-Transform-Load (ETL)

(Semantic)
Trajectory
aggregations
(DW)



### Key questions that arise



- How to reconstruct trajectories from raw logs?
- How to **store trajectories** in a DBMS?
- What kind of analysis is suitable for mobility data (in particular, trajectories of moving objects)?
  - How does infrastructure (e.g. road network) affect this analysis?
- Which patterns / models can be extracted from them?
  - Clusters, frequent patterns, anomalies / outliers, etc.
  - How to compute such patterns / models efficiently?
- How to protect privacy user anonymity?
  - What is the trade-off between privacy protection and quality of analysis?
- Which are the semantics hidden into mobility data?
- What if extremely large volumes of data are collected?

1.5. Summary

# Summarizing ...



- Mobility data management and exploration is a hot research topic
  - due to the wide spread of GPS devices
- In this chapter, we discussed:
  - the concept of mobility data
  - what can we learn from mobility data
  - the core applications for mobility data (traffic analysis, LBS/LBSN)
  - the technical challenges from the data management perspective

