Mobility Data Management & Exploration

Ch. 09. Semantic Aspects on Mobility Data



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"The map in not the territory." Alfred Korzybski

Chapter outline



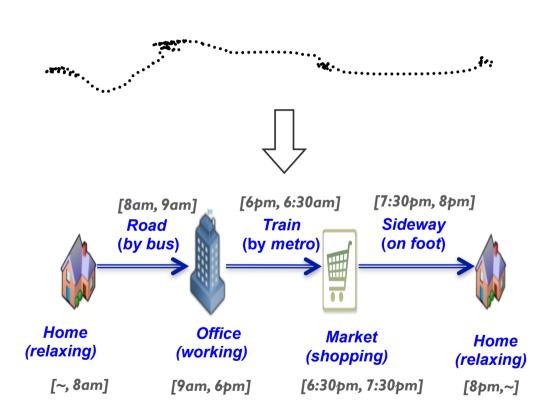
- 9.1. From Raw to Semantic Trajectories
- 9.2. The Semantic Enrichment Process of Raw Trajectories
- 9.3. Semantic Trajectory Data Management
- 9.4. Semantic Trajectory Data Exploration
- 9.5. Semantic Aspects of Privacy
- 9.6. Summary

9.1. From raw to semantic trajectories

From "raw" to "semantic" trajectories

- From raw ...
 - sequences of (x,y,t) points, e.g., GPS feeds

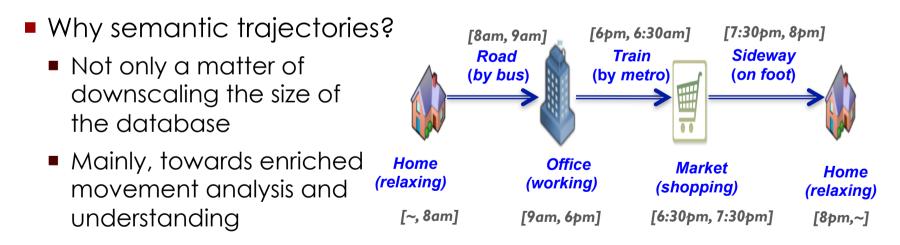
- ... to meaningful mobility tuples <where, when, what/how/why>
 - Semantic Trajectory:
 T = {e_{first},...,e_{last}}
 - Episode: e_i = (STOP | MOVE, t_{from}, t_{to}, place, tag)



Semantic trajectory



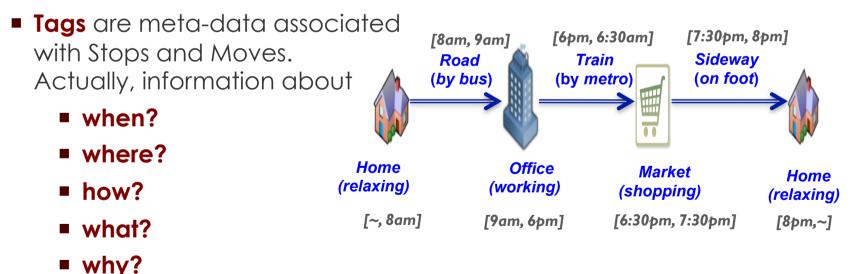
- An alternative (semantically-annotated) representation of the motion path of a moving object
- Detection of homogenous fractions of movement,
 - A trajectory is reconstructed as a sequence of episodes (stops/ moves) along with appropriate tags



Semantic trajectory (cont.)



- A trajectory is reconstructed as a sequence of episodes (stops/ moves) along with appropriate tags
 - Stops are the parts of the object's trajectory during which the object stays "static" at a place
 - Moves are the parts of the object's trajectory in between two Stops, i.e. where the object is "moving"



9.2. The semantic enrichment process of raw trajectories

Semantic trajectory enrichment

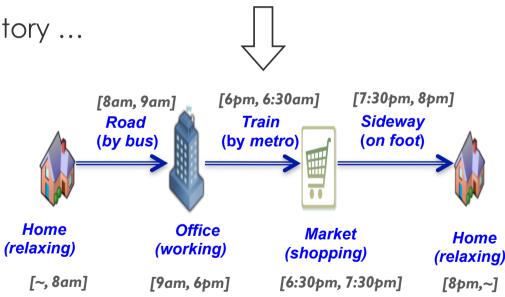


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 The process of adding application-oriented contextual information to raw trajectories

......

- Input: a 'valid' raw trajectory ...
 - Recall Chap. 3
- ... plus a contextual data repository
- Output: a semantic trajectory



Semantic trajectory enrichment (cont.)

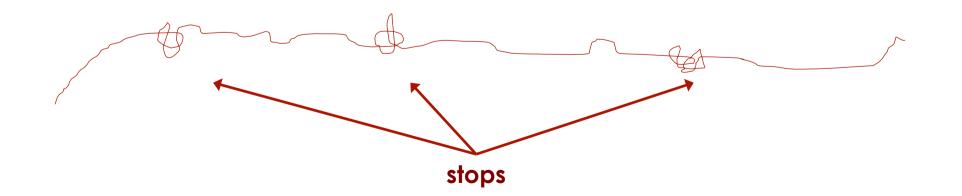
- Necessary intermediate step: trajectory segmentation
- partition the trajectory into sub-trajectories that 100 correspond to a specific behavior or activity Examples: [6pm, 6:30am] [7:30pm, 8pm] Detecting stops and moves, [8am, 9am] Train Sideway Road Detecting changes in (on foot) (by bus) (by metro) movement pattern, etc. Home Office Market Home (relaxing) (working) (shopping) (relaxing) [~, 8am] [9am, 6pm] [6:30pm, 7:30pm] [8pm,~]

Stop discovery



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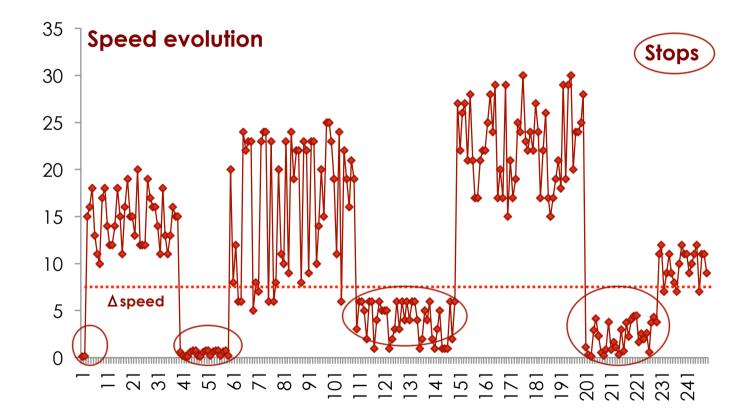
- Issue: How can Stop be detected in a raw trajectory?
- Solutions:
 - when the trajectory intersects the geometry of a POI and the duration of intersection is above a given temporal duration threshold: SMoT technique (2007)
 - when dense areas of the trajectory points are detected, using e.g. a density-based clustering algorithm, and those areas are mapped to a POI: CB-SMoT technique (2008)



Stop discovery (cont.)



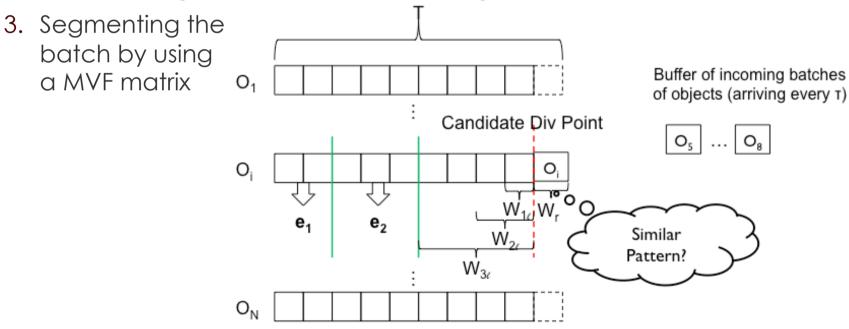
Alternative: velocity-based stop identification



Online trajectory segmentation



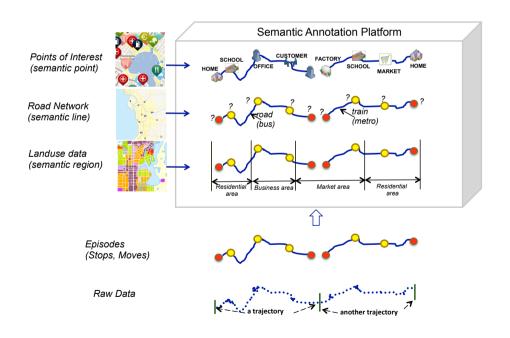
- Quite useful in traffic monitoring scenarios
- An approach: **SeTraStream** (2011). Works in 3 steps:
 - 1. Cleaning and smoothing the incoming batch of status updates
 - status updates are described by Movement Feature Vectors (MVF)
 - 2. Compressing the batch by considering MVF characteristics



Semantic annotation of episodes

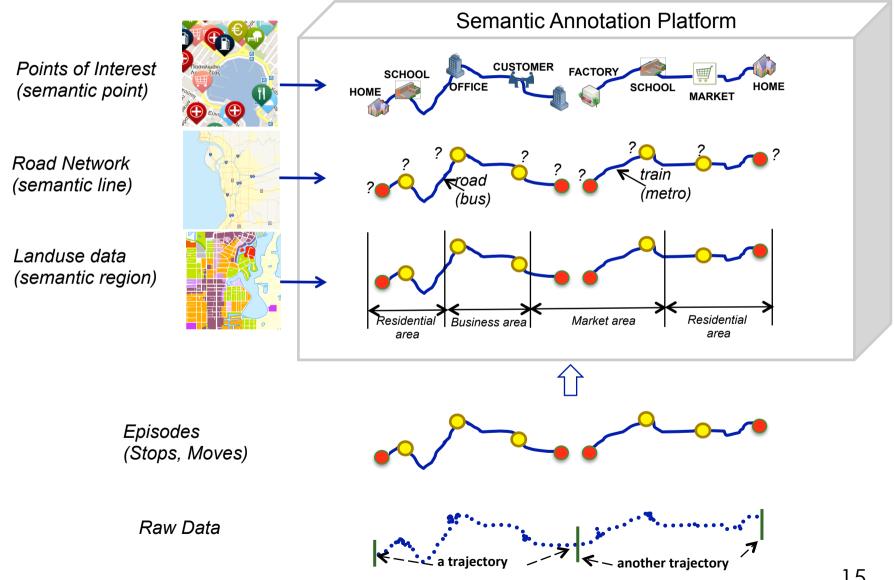


- ... a complete framework: SeMiTri (2011-12)
- Three layers:
 - 1. Semantic regions: annotate trajectories with geographic regions of interest ROIs (using OpenStreetMaps)
 - 2. Semantic lines: annotate trajectories with e.g. road network
 - 3. Semantic points: annotate Stops with POI types instead of POIs (using Hidden Markov Model)



The SeMiTri framework





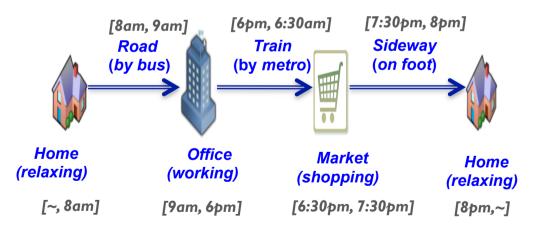
9.4. Semantic trajectory data management

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STD management requirements



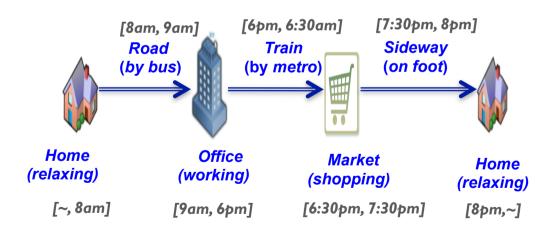
- Efficient support of both raw and semantic trajectory databases (TD and STD, resp.)
- Indicative queries:
 - "Search for people who follow the home office home pattern every weekday"
 - "Search for people who cross the city center on their way from office back to home"
 - "Search for people who make long trips (e.g. more than 20 km) on their way from home to office without including intermediate stops"



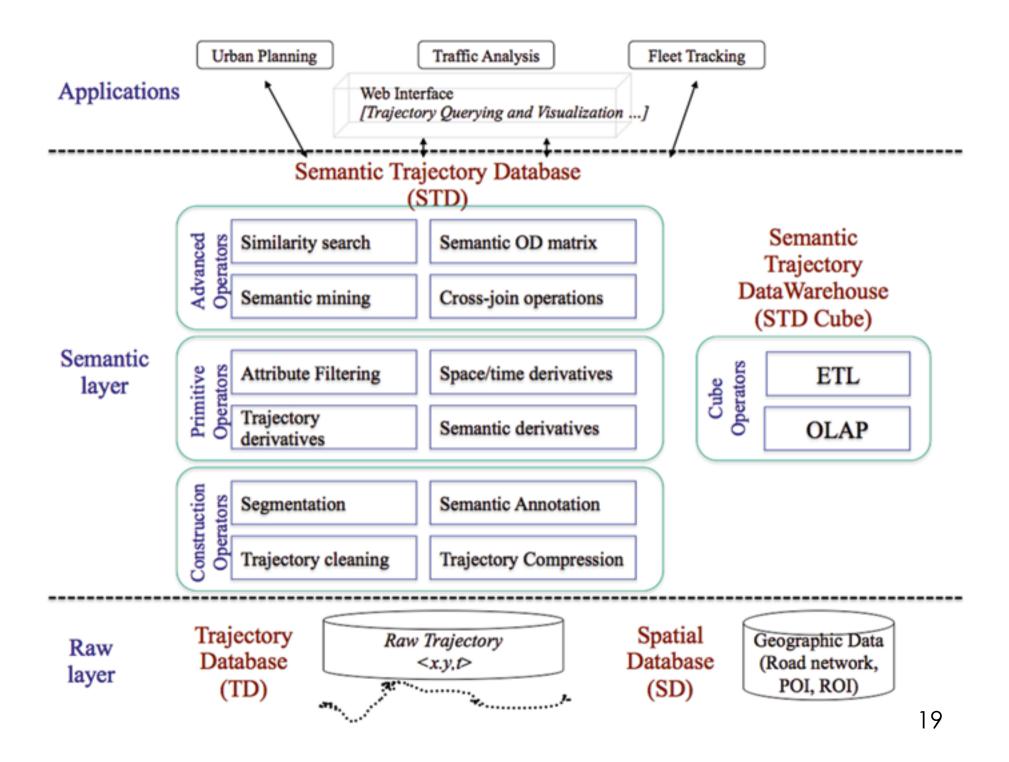
STD management requirements (cont.)

- Such queries are innovative and cannot be handled effectively and efficiently by existing approaches and corresponding MOD engines
- Moreover, by maintaining a semantic trajectory data cube, we are able to support analysis of type:
 - "when, where and why moving objects of a specific profile stop?"
 - "when, how and where from/to moving objects of a specific profile move?"

. . .



The 'big picture' of a semantic trajectory DB/DW infrastructure



A data type system for STD

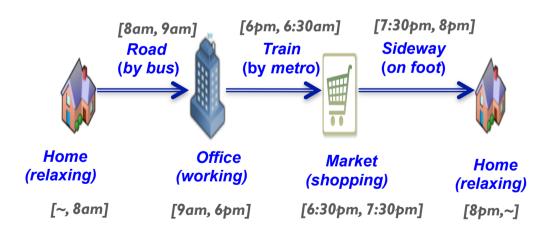


- Two novel datatypes, 'episode' and 'semantic trajectory'
 - corresponding to raw sub-trajectory and raw trajectory, resp.
- episode: a tuple (defineTag, MBB, episodeTag, activityTag, Tlink), where:
 - defineTag: a flag in {Stop, Move}
 - MBB: a tuple (MBR, t_{start}, t_{end}) [6pm, 6:30am] [7:30pm, 8pm] [8am, 9am] corresponding to the 3D Sidewav Road Train coverage of the respective (by bus) (by metro) (on foot) raw sub-trajectory episodeTag and Home Office activityTag: Market Home (relaxing) (working) (shopping) (relaxing) semantic information [~, 8am] [9am, 6pm] [6:30pm, 7:30pm] [8pm,~] T-link: link to the respective raw sub-trajectory

A data type system for STD (cont.)



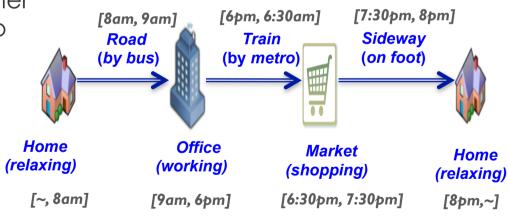
- Two novel datatypes, 'episode' and 'semantic trajectory':
 - corresponding to raw sub-trajectory and raw trajectory, resp.
- semantic trajectory: a tuple (o-id, semtraj-id, T_{sem}), where:
 - o-id: the moving object identifier
 - sem-traj-id: the semantic trajectory identifier
 - T_{sem}: a sequence of episodes, {e₁, ..., e_n}, ordered in time



A data type system for STD (cont.)



- Primitive methods and operators on 'episode' datatype:
 - number duration (), number length (), number avg-speed (): returns the duration, length, average speed, resp., of the episode
 - geometry PAA (): returns the Potential Area of Activity (PAA) of the episode
 - boolean intersects (MBB b): returns true or false, whether episode's MBB intersects b or not



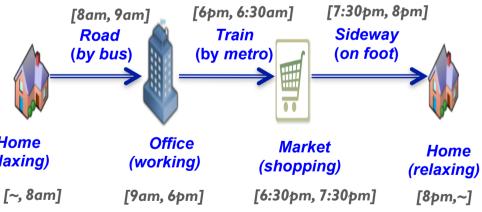
A data type system for STD (cont.)



- Primitive methods and operators on 'semantic trajectory' datatype:
 - number num_of_episodes (string tag),

set[episode] **episodes_with** (string tag): returns the number of episodes or the episodes themselves, resp., of the semantic trajectory that include tags LIKE tag

- sem_trajectory confined_in (geometry g, timeperiod p, string tag): returns a portion of the semantic trajectory consisting of episodes that
 - spatially overlap with g, Home (relaxing)
 - temporally intersect with p, and
 - textually match with tag

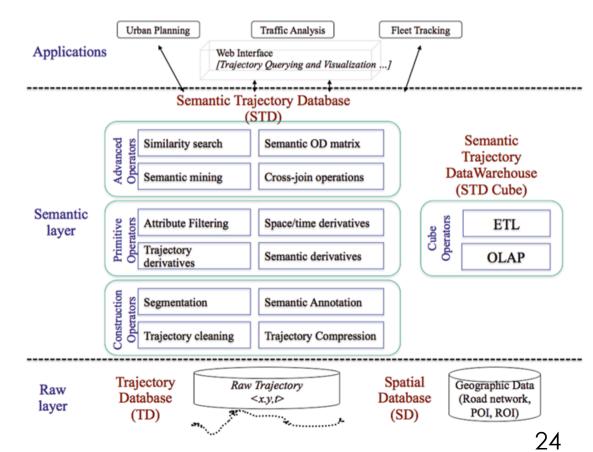


Querying STD



- Having such methods and operators in our hands, several types of queries can be defined:
 - Q1 type: raw trajectory queries (involving TD)
 - Example: "Search for people who crossed park X at night"
 - Q2 type: semantic trajectory queries (involving STD)

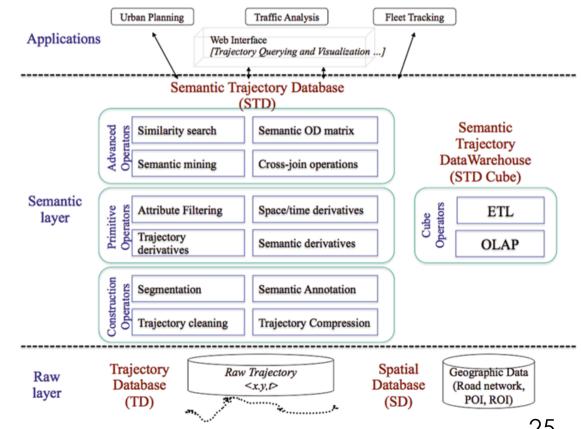
 Example: "Search for people who follow the pattern home – office – home every weekday"



Querying STD (cont.)



- Having such methods and operators in our hands, several types of queries can be defined:
 - ...
 - Q3 type: cross-over semantic trajectory queries (involving both TD and STD)
 - Example: "Search for people who cross the city center on their way from office back to home"
 - Technically supported through T-link (recall the def. of episode datatype)



Indexing STD



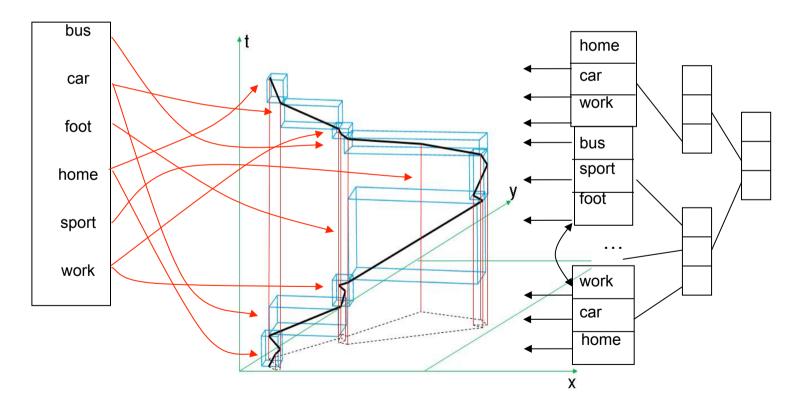
- Issue: equally manage the spatio-temporal and the semantic (textual) component of semantic trajectories
- Baseline solutions:
 - Spatio-textual indexing structures (e.g. R-trees enhanced with textual search capabilities)
 - Trajectory data structures (e.g. TB-trees) along with text indexes (e.g. inverted files)
- A proposal: Semantic Trajectory Bundle (STB) tree
 - Builds upon spatio-temporal information of episodes (TB-tree) ...
 - ... also maintaining their textual information (inverted file)

Indexing STD (cont.)



STB-tree (2013)

- a TB-tree enhanced with textual information (right) ...
- ... along with an inverted file on tags (left)

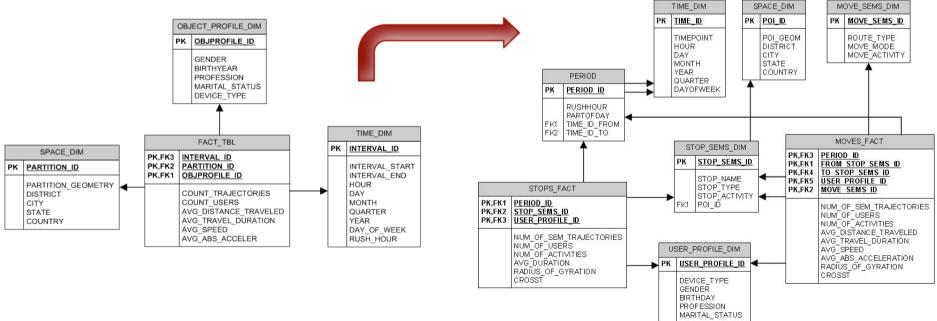


9.4. Semantic trajectory data exploration

From raw to semantic TDW



- Extend TDW (recall Chap. 6) with dimensions and facts about:
 - STOPS: who made a stop? when and where? What did she do during her stop?
 - MOVES: who made a movement? when and where from/to? How did she move and what did she do during her motion?



A semantic trajectory data cube

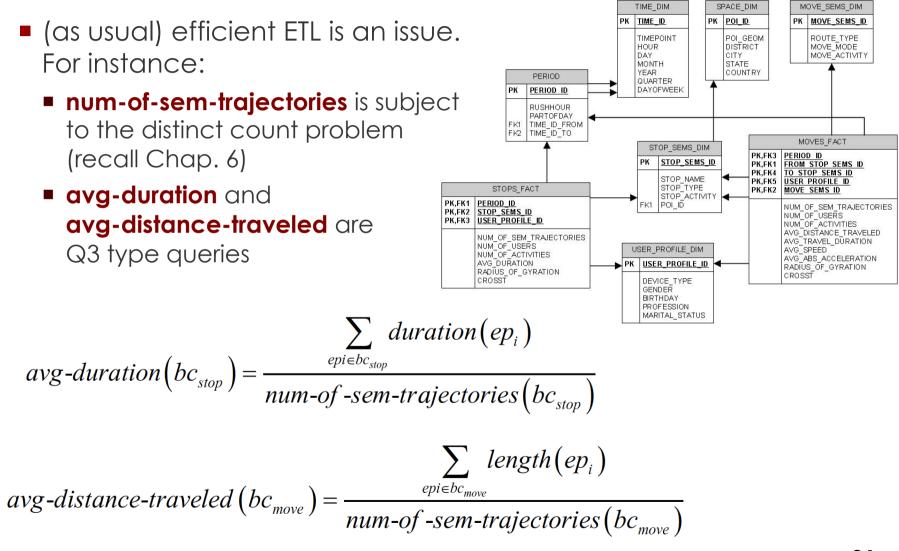


5 dimensions:

Space, Time, User_Profile TIME DIM SPACE DIM MOVE SEMS DIM (as in raw TDW) PK POI ID MOVE SEMS ID PK TIME ID PK Stop_Sems, Move_Sems: ROUTE TYPE TIMEPOINT POI GEOM DISTRICT HOUR MOVE MODE semantics about DAY CITY MOVE ACTIVITY MONTH STATE YEAR COUNTRY Stops and Moves PERIOD QUARTER DAYOFWEEK PK PERIOD ID RUSHHOUR 2 fact tables: PARTOFDAY FK1 TIME ID FROM FK2 TIME ID TO STOPS Fact MOVES FACT STOP SEMS DIM PK.FK3 PERIOD ID MOVES_Fact PK STOP SEMS ID PK.FK1 FROM STOP SEMS ID PK.FK4 TO STOP SEMS ID STOP NAME PK,FK5 USER PROFILE ID STOPS FACT STOP TYPE PK,FK2 MOVE SEMS ID STOP_ACTIVITY PK,FK1 PERIOD ID FK1 POI ID NUM OF SEM TRAJECTORIES PK,FK2 STOP SEMS ID NUM OF USERS USER PROFILE ID PK,FK3 NUM OF ACTIVITIES AVG DISTANCE TRAVELED NUM_OF_SEM_TRAJECTORIES AVG TRAVEL DURATION NUM OF USERS USER PROFILE DIM AVG SPEED NUM OF ACTIVITIES AVG ABS ACCELERATION AVG DURATION USER PROFILE ID PK RADIUS OF GYRATION RADIUS OF GYRATION CROSST CROSST DEVICE TYPE GENDER BIRTHDAY PROFESSION MARITAL STATUS

ETL in semantic trajectory data cubes





Mining STD



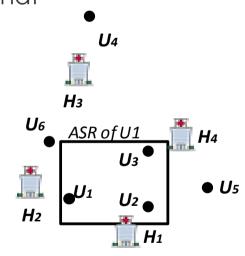
- Semantic trajectory mining is an infant, very challenging field, for analysis purposes
- Example (from clustering):
 - Try to discover a pattern like "this group of students (coming from different origins) stopped at piazza P participating in a protest for an hour; then walked to café C where they stayed for half an hour; and finally they went by tram T to bar B where they partied until midnight"
 - Constraints of types who? when? where? what? how?
- Critical technical objective: semantic trajectory similarity function. Alternative roadmaps:
 - Map semantic trajectories into vectors in a feature space (features may include spatial, temporal, and textual aspects)
 - Define an aggregate function between dissimilarity in spatiotemporal and dissimilarity in semantic (textual) space.

9.5. Semantic aspects of privacy

LBS for sensitive semantic locations



- What if an adversary is aware of the semantic whereabouts of a territory? May be able to extract sensitive personal information
 - Hence, sensitive locations should be somehow protected
- An idea: semantic location cloaking along with I-diversity (2011)
 - Location is generalized to a cloaked region (CR) that includes at least K LBS users (recall Chap. 8) and at least I different POIs (recall Chap. 2)
 - However, we cannot avoid semantic location identification attacks
- Another idea: maintain a set of strongly CRs (2012)
 - Supports personalized privacy profile:
 - sensitive vs. non-sensitive POIs
 - the maximum probability of linking a user with a sensitive place



Privacy in STD



- Applying K-anonymity in semantic trajectories is not enough:
 - Example: all K trajectories stop at a clinic (sensitive place)
- An idea: C-safe Anonymization of Semantic Trajectories (CAST, 2011)
 - Produces a sanitized (c-safe) version of a semantic trajectory ...
 - by generalizing at the semantic level (place taxonomy)
 - ... under the assumption that an adversary is aware of
 - the utilized anonymization process
 - the place taxonomy
 - the presence of a user in the dataset
 - the quasi-identifier sequence of visited places

9.6. Summary

Summarizing ...



- (as for their raw counterparts) semantic aspects of mobility data ask for effective and efficient modeling, management, and knowledge discovery
- In this chapter, we presented:
 - How to model a semantic trajectory, from the abstract concept to the datatype level
 - The types of queries that are of interest in a STD
 - and how to index an STD for efficient query processing
 - The emerging challenges for STD mining and privacy

End of chapter